

**TURCK**

Your Global Automation Partner

...Y1...

# Inductive Safety Sensors



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# 1 About this safety manual

**DANGER**

Malfunction caused by operating errors

**Danger to life if safety function fails!**

- ▶ Observe the instructions contained in this safety manual without fail if the device is to be used in safety-related applications.

This safety manual contains instructions on the use of devices in safety instrumented systems (SIS). The consideration of safety-related values is based on IEC 61508, ISO 13849-1 IEC 62061. The safety manual describes the values determined for the SIL and PL assessment and is only applicable in conjunction with the attached TÜV certificate 968/FSP 1358.02/23. Read this document carefully before using the device. This will prevent the risk of personal injury or damage to property or equipment. Keep this manual safe during the service life of the device. If the device is passed on, hand over this safety manual as well.

## 1.1 Target groups

This safety manual is designed for use by suitably qualified and trained personnel and must be read and followed by anyone entrusted with any of the following tasks:

- Unpacking and mounting
- Commissioning
- Setting
- Testing and maintenance
- Troubleshooting
- Disassembly and disposal

## 1.2 Explanation of symbols

The following symbols are used in this safety manual:

**DANGER**

DANGER indicates an immediate hazardous situation, which, if not avoided, will result in death or serious injury.

**NOTE**

NOTE indicates tips, recommendations and important information. The notes simplify work, contain information on particular operating steps and help to avoid additional work resulting from incorrect procedures.

**MANDATORY ACTION**

This symbol denotes actions that the user must carry out.

## 1.3 Applicable documents

- Individual data sheet of the device concerned (see [www.turck.com](http://www.turck.com))
- TÜV certificate 968/FSP 1358.02/23 (see Appendix)

## 1.4 Abbreviations and terms

Definition of terms, see IEC 61508-4 and ISO 13849-1.

<b>DC</b>	diagnostic coverage device type
<b>E/E/PE system</b>	electrical/electronic/programmable electronic system
<b>EUC</b>	equipment under control
	dangerous failure
	no effect failure
	no part failure
	safe failure
	safe state
<b>HFT</b>	hardware fault tolerance
	high demand mode
	low demand mode
<b>MooN</b>	M out of N channel architecture
<b>MTBF</b>	mean time between failures
<b>MTTF</b>	mean time to failure
<b>MTTF<sub>d</sub></b>	mean time to dangerous failure
<b>MTTR</b>	mean time to restoration
<b>PF<sub>D SPEC</sub></b>	probability of dangerous failure on demand
<b>PF<sub>D AVG</sub></b>	average probability of dangerous failure on demand
<b>PFH</b>	average frequency of dangerous failure per hour
<b>PL</b>	performance level
<b>PTC</b>	proof test coverage
<b>PSTC</b>	partial stroke test coverage
<b>SFF</b>	safe failure fraction
<b>SIF</b>	safety instrumented function
<b>SIS</b>	safety instrumented system
<b>SIL</b>	safety integrity level
	reaction time
	proof test
	proof test interval
	total failure rate
	$\lambda_{\text{dangerous undetected}}$
	$\lambda_{\text{dangerous}}$
	$\lambda_{\text{safe}}$

## 1.5 Document history

Rev.	Description	Date
1.0.0	First edition	02.04.2015
1.1.0	Renewal of SIL certificate and report	01.03.2016
2.0.0	Renewal of SIL certificate, intended use extended to the area of ISO 13849-1	16.01.2017
2.1.0	Renewal of SIL certificate	21.11.2017
3.0.0	Updates: – Useful life – Decommissioning – Withdrawing from service	13.10.2020
3.1.0	Renewal of SIL certificate Correction of FIT value Updates: – Reaction time	12.05.2023
3.2.0	Updates: Layout changes, references to SIL card removed, PTC added under section 4.4.4.	24.09.2025

The German version shall be considered the definitive document. Every care was taken in the production of the translations of this document. If there is any uncertainty in its interpretation, refer to the German version of the safety manual or contact TURCK directly.



### NOTE

In all cases use the latest version of this safety manual. Check whether a newer version is available.

## 2 Notes on devices

### 2.1 Device variants

This safety manual is applicable to ...Y1... series inductive sensors, see TÜV certificate 968/FSP 1358.02/23, type code.

### 2.2 Scope of delivery

Devices in a threaded barrel are supplied with two fixing nuts. Devices in M5, M8 or M12 housings as well as devices with a special surface coating (PTFE) are also supplied with two lock washers.

### 2.3 TURCK service

TURCK supports you in your projects — from the initial analysis right through to the commissioning of your application. The TURCK product database at [www.turck.com](http://www.turck.com) offers you several software tools for programming, configuring or commissioning, as well as data sheets and CAD files in many export formats.

For the contact details of our branches worldwide, please see page 20.

### 3 For your safety

The devices are designed according to the latest state-of-the-art technology. Residual hazards, however, still exist.

Observe the following warnings and safety regulations in order to prevent danger to persons and property. TURCK accepts no liability for damage caused by failure to observe these regulations.

#### 3.1 Intended use

The TURCK ...Y1... series inductive sensors are provided with a standard NAMUR output. These sensors enable the creation of safety-related systems:

	IEC 61508		ISO 13849-1
	Low Demand	High Demand	(Table 3)
1-channel (HFT 0)	SIL1/SIL2	SIL1	PL c
2-channel (HFT 1)	SIL3	SIL3	PL e

The sensors are 100 % compatible with all standard NAMUR processing units as well as with (safety) PLC systems with NAMUR inputs. The sensors are **not** provided with internal fault diagnostics (Diagnostic Coverage DC = 0) and are classified as device type A (non complex device).

When used in safety systems, the probability of dangerous failure (PFD) and the hardware fault tolerance for the entire circuit must be determined and given due consideration.

#### 3.2 Obvious misuse

Apart from the target, metal objects must not be situated or brought into the area of the active face or in the metal-free zone (refer to the relevant data sheet).

### 3.3 General safety regulations

- The device must be registered online at <https://www.turck.com/SIL> .
- It is the responsibility of the user to ensure that the device is used in compliance with the applicable regulations, standards and laws.
- The suitability for specific applications must be assessed by considering the particular overall safety-related system with regard to the requirements of IEC 61508 and ISO 13849-1 (table 3).
- The device must only be carried out by trained and qualified personnel.
- The device must only be commissioned and operated by trained and qualified personnel.
- A function test must be completed prior to initial operation, after each parameter setting, after repair and replacement, as well as at the stipulated interval T[Proof].
- When the device is in operation, ensure that the power supply is within the specified voltage range.
- Ensure regularly that the plug connections and cables are always in good condition.
- Special application-specific factors such as chemical and physical stresses may cause the premature wear of the devices and must be taken into consideration when planning systems; take special measures to compensate for a lack of experience based values, e.g. through the implementation of shorter test intervals.
- If faults occur in the device that cause a switch to the defined safe state, measures must be taken to maintain the safe state during the further operation of the overall control system.
- TURCK must be notified of dangerous failures immediately.
- A faulty device must be replaced immediately and must not be repaired.
- The device must be replaced immediately if the connector is faulty or the device has any visible faults.
- Interventions and conversions on the device are not permissible. Repairs must only be carried out by TURCK. Return the device to TURCK for this (see section "Repair").
- Ensure the use of the closed-circuit current principle for all external safety circuits connected to the system.
- Before using the product in safety-related applications, the suitability of the specifications stated in this safety manual for the particular application (e.g. particular branch-specific requirements and practices) must always be checked. In cases of doubt please contact the stated manufacturer's address.

## 4 Device specific information on safety applications

### 4.1 Safety function

In an undamped state, the current consumption is  $> 2.1$  mA and  $< 6$  mA. Both a wire break ( $< 0.2$  mA) as well as a short circuit ( $> 6$  mA) of the sensor cable are defined as safe failures; these failures must be detected in the processing unit.

### 4.2 Functions and operating modes

The sensors produce a change in the electrical output signal in the proximity of metal objects. This change complies with EN 60947-5-6:2000. The output behavior of the inductive sensors has the following characteristics:

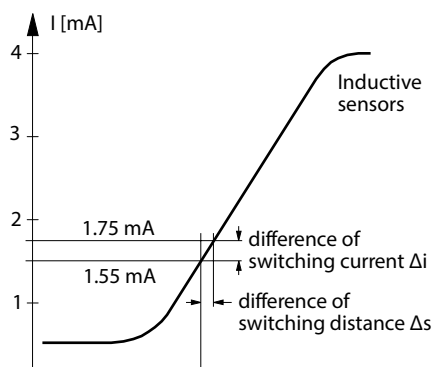


Abb. 1: NAMUR characteristic curve as per EN 60947-5-6

Inductive sensors with a NAMUR output have the following features:

- The current is  $< 1.2$  mA and  $> 0.2$  mA when a target is detected. The sensor is “damped”.
- Ideal switch point:  $(1.55 \pm 0.2)$  mA at a switching distance  $S_n$
- Current consumption on wire break:  $< 0.2$  mA
- Current consumption on short circuit:  $> 6$  mA
- Undefined state: 1.2 mA to 2.1 mA
- If there is no target present, the current is  $> 2.1$  mA to 6 mA. The sensor is “undamped”.

These values are based on standard targets as per EN 60947-5-2:2014.

- Rectangular, steel 1 mm thick
- Edge length is the greatest value of either
  - $3 \times$  rated operating distance or
  - the diameter of the active face

### 4.3 Types of faults and failures

Failures must be classified in conjunction with the application into safe (non-hazardous) and unsafe (hazardous) failures. You as the operator are responsible for this.



**NOTE**

TURCK must be notified of all damage that was caused by a dangerous undetected failure.

## 4.4 Safety characteristic values

### 4.4.1 FMEDA assumptions

The safety-related characteristic values were determined based on an FMEDA in accordance with IEC 61508. The FMEDA is based on the following assumptions:

- The failure rates are constant.
- The mechanical wear is not considered.
- The propagation of failures is not relevant.
- The device is operated in low demand mode.
- The failure rates of an external power supply are not considered.
- The failure rates used are the Siemens standards SN 29500 at 40 °C.
- The ambient conditions correspond to an average industrial environment, as defined in MIL-HNBK-217-F or IEC 60654-1, Class C (sheltered location).
  - The ambient temperature is normally 40 °C.
  - A safety factor of 2.5 must be applied for ambient temperatures of 60 °C and frequent temperature fluctuations.

### 4.4.2 Machine safety

The suitability for machine safety applications is based on the transfer of the average probability of dangerous failure per hour (PFH) determined from the FMEDA (see 4.4.1) as per table 3 of ISO 13849-1.

### 4.4.3 Hardware architecture

The device is considered as a Type A component (non complex). The hardware fault tolerance HFT is 0.

### 4.4.4 Characteristic values for ...Y1... NAMUR sensors

Parameters	Value
Device Type	A (acc. to IEC 61508-2)
Total Failure Rate $\lambda_S + \lambda_D$	28.5 FIT
Lambda dangerous = Lambda dangerous undetected $\lambda_{DU}$	3.1 FIT
Lambda safe $\lambda_S$	25.2 FIT
Safe Failure Fraction (SFF)	88.4 %
MTTF <sub>d</sub>	36471 a
PFH (1oo1)	31 E-09 1/h
PFD <sub>av</sub> (T = 20a) (1oo1)	2.7 E-04
Safety Capability (the requested HFT on the relevant application standard has to be considered)	SIL3, PL e
Reaction time	< 1 ms
PTC	100 %

## 4.5 Recurrent function tests

A function test must be completed prior to initial operation, after each parameter setting, after repair and replacement, as well as at the stipulated interval T[Proof]:

- ▶ Ensure that the function test is only carried out by qualified personnel.
- ▶ Think first about your safety and the safety of your environment. If in doubt, replace the device.
- ▶ Use a standard target according to EN 60947-5-2 for the function check.
- ▶ Move the standard target to the active face of the sensor to a point up to  $1.21 \times$  rated switching distance.  
Ensure here that the switching state has not changed.
- ▶ Move the standard target to the active face of the sensor to a point up to  $0.81 \times$  rated switching distance.  
Ensure here that the switching state has changed.
- ▶ Repeat the above tests with the actual target present. Move the target to the active face of the sensor within the distances present during normal operation.
- ▶ Check whether the sensor is mounted securely.
- ▶ Check that the mounting is complete (housing cover, use of the supplied lock washers, that the sensor is undamped in the normal operating state of the installation etc.).
- ▶ Check for proper cable entry and correct mounting of the male connector.
- ▶ Check the general condition of the device, such as for cracks in the housing or damage.

## 4.6 Useful life

Experience has shown that the useful lifetime often lies within a range of 8 to 12 years. It can be significantly less if elements are operated near their specification limits or if they are exposed to harsh environmental conditions. However, on the other hand it can be extended by appropriate measures. For example, heavy temperature fluctuations could potentially decrease the useful lifetime, as constant temperature below 40 °C could potentially increase the useful lifetime.

## 4.7 Special regulations and restrictions

**NOTE**

Each application has its particular conditions of use and ambient requirements. For this reason, the safety-related assessment of a system must always take the actual process into account – in addition to the general statements concerning probability of failure, tolerances and failure rates of the components. Special application-specific factors such as chemical and physical stresses may thus cause the premature wear of the devices and must therefore be taken into consideration already during the planning stage of a system. Take special measures to compensate for a lack of experience based values, e.g. through the implementation of shorter test intervals. The estimation of the diagnostic coverage (DC) can vary from application to application. The estimation of the hardware fault tolerance (HFT) can only take place if the use of the compliant object is restricted.

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## 5 Installation and commissioning

### 5.1 Mounting

Depending on type, the sensors must be mounted either flush or non-flush (see the relevant data sheet at [www.turck.com](http://www.turck.com)). Any mounting accessories required are also shown in the product data sheet.



#### **NOTE**

##### **Requirements for safety-related mounting:**

- ▶ With safety-related applications, only mount the sensor so that it is undamped when the installation is in a normal operating state.



#### **WARNING!**

Non-safety-related mounting

##### **Risk of injury from device faults!**

For a non-safety-related mounting, the sensor is damped in the normal operating state of the system.

- ▶ With these mounting conditions do not use the sensor in safety-related applications as the safety function will be deactivated in this state.



#### **WARNING!**

Incorrect mounting

##### **Risk of injury due to malfunction or sensor failure**

- ▶ Observe the relevant mounting conditions of the sensor (see data sheet).
  - ▶ Observe, in particular the tightening torques of the housing nuts and fixing screws.
  - ▶ Use the lock washers if supplied.
-

## 5.2 Connection

### 5.2.1 Devices with male connector

- ▶ Connect the female connector of the connection cable to the male connector of the sensor.
- ▶ Connect the open end of the connection cable to the power source and/or processing units as shown in the wiring diagram and the terminal layout of the connected sensor (see data sheet).

### 5.2.2 Devices with a connection cable

- ▶ Connect the open end of the connection cable to the power source and/or processing units as shown in the wiring diagram and the terminal layout of the connected sensor (see data sheet).

### 5.2.3 Devices with a terminal chamber

- ▶ Connect the open end of the connection cable to the sensor according to the following wiring diagram.
- ▶ Connect the other open end of the connection cable to the power source and/or processing units as shown in the wiring diagram and the terminal layout of the connected sensor (see data sheet).

### 5.2.4 Wiring diagrams

Refer here to the wiring diagrams of the sensors in the corresponding data sheet.

## 5.3 Commissioning

When the device is in operation, ensure that the power supply is within the specified voltage range.



### **DANGER**

Malfunction caused by operating errors

### **Danger to life if safety function fails!**

- ▶ A function test must be completed prior to initial operation, after each parameter setting, after repair and replacement, as well as at the stipulated interval T[Proof].

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The sensor is operational within 80 ms after the power supply is connected and switched on.

## 5.3.1 Selecting processing units

The sensors must be operated with processing units compliant with EN 60947-5-6:2000. These processing units must monitor wire breaks and short circuits and switch to a safe state at currents  $< 0.2$  mA (wire break) and  $> 6$  mA (short circuit). The processing unit must also comply with a suitable SIL certification in accordance with IEC 61508 and Performance Level according to ISO 13849-1.

Ensure that the devices and the housing materials are suitable for the application. For this refer also to the applicable data sheets of the TURCK devices at [www.turck.com](http://www.turck.com).

## 6 Operation, maintenance and repair

### 6.1 Operation

#### Normal operation

During normal operation, the LED indicates the switching state of the sensor as follows (only with devices with LED display):

LED indication	Meaning
on	No target detected, output current $> 2.1$ to $6$ mA, "Output not switched"
off	Target detected, output current $> 0.2$ to $1.2$ mA, "Output switched"

### 6.2 Troubleshooting

#### 6.2.1 Ambient interference

Observe the mounting instructions in the relevant data sheets of the sensors in order to prevent any ambient interference.

#### 6.2.2 Device faults

If the device does not function as expected, first check whether ambient interference is present. If this is not the case, a device fault is present. In this case, decommission the device and replace it with a new device of the same type. Notify TURCK of any safety-related faults on the device.

### 6.3 Maintenance

Ensure regularly that the plug connections and cables are always in good condition. The devices are maintenance-free, clean dry if required.



#### **DANGER**

Malfunction caused by conductive media or static charge

**Danger to life if safety function fails!**

► When cleaning do not use any liquid media or statically charging cleaning agents.

## 6.4 Repair

**DANGER**

The device must not be repaired.

**Danger to life due to malfunction!**

- ▶ Send the device to TURCK for repair. Observe here the specific warranty conditions agreed with the shipment.

**DANGER**

Malfunction caused by operating errors

**Danger to life if safety function fails!**

- ▶ A function test must be completed prior to initial operation, after each parameter setting, after repair and replacement, as well as at the stipulated interval T[Proof].

### 6.4.1 Returning devices

If a device has to be returned, bear in mind that only devices with a decontamination declaration will be accepted. This is available at <http://www.turck.de/en/retoure-service-6079.php> and must be completely filled in, and affixed securely and weather-proof to the outside of the packaging.

## 7 Decommissioning and withdrawal from service

### 7.1 Decommissioning

- ▶ Remove the connection cable from the power supply and/or processing units.
- ▶ Disconnect the connection cable from the sensor.
- ▶ Undo the connections of the sensor or the mounting aid for the mounting environment.
- ▶ If necessary, undo the connection of the sensor to the mounting aid.

### 7.2 Withdrawing from service




Devices must be properly disposed of and must not be included in general household garbage.

## 8 Appendix

## 8.1 TÜV certificate 968/FSP 1358.02/23

# Certificate



**Nr./No.: 968/FSP 1358.02/23**

<b>Prüfgegenstand</b> <b>Product tested</b>	Induktive, magnetisch-induktive und kapazitive Näherungsschalter Proximity Switches with NAMUR Interface	<b>Zertifikatsinhaber</b> <b>Certificate holder</b>	Werner Turck GmbH & Co. KG Goethestr. 7 58553 Halver Germany
<b>Typbezeichnung</b> <b>Type designation</b>	...-...-Y1-.../... (Details see backside of this certificate)		
<b>Prüfgrundlagen</b> <b>Codes and standards</b>	EN ISO 13849-1:2015	EN 61508 Parts 1-7:2010	
<b>Bestimmungsgemäße Verwendung</b> <b>Intended application</b>	Sensoren für den Einsatz in Sicherheitsfunktionen bis SIL 3 und PL e: In einkanaliger Konfiguration (HFT=0) bis SIL 1 nach EN IEC 62061:2021, EN 61511-1:2017+ A1:2017, EN 61508 und PL c nach EN ISO 13849-1, oder SIL 2 nach EN 61511-1:2017+ A1:2017, EN 61508 (nur Low Demand Mode). In zweikanaliger Konfiguration (HFT=1) bis SIL 3 nach EN IEC 62061:2021, EN 61511-1:2017+ A1:2017, EN 61508 und PL e nach EN ISO 13849-1. Sensors for use in safety functions up to SIL 3 and PL e: In single channel configuration (HFT=0) up to SIL 1 of EN IEC 62061:2021, EN 61511-1:2017+ A1:2017, EN 61508 and PL c of EN ISO 13849-1, or SIL 2 of EN 61511-1:2017+ A1:2017, EN 61508 (low demand mode only). In dual channel configuration (HFT=1) up to SIL 3 of EN IEC 62061:2021, EN 61511-1:2017+ A1:2017, EN 61508 and PL e of EN ISO 13849-1.		
<b>Besondere Bedingungen</b> <b>Specific requirements</b>	Die Hinweise in der zugehörigen Installations- und Betriebsanleitung sowie im Safety Manual sind zu beachten. The instructions of the associated Safety, Installation and Operating Manual shall be considered.		

Zusammenfassung der Testergebnisse siehe Rückseite des Zertifikates.  
Summary of test results see backside of this certificate.

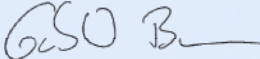
Gültig bis / Valid until 2028-05-12

Der Ausstellung dieses Zertifikates liegt eine Evaluierung entsprechend dem Zertifizierungsprogramm CERT FSP1 V1.0:2017 in der aktuellen Version zugrunde, deren Ergebnisse im Bericht Nr. 968/FSP 1358.02/23 vom 08.05.2023 dokumentiert sind. Dieses Zertifikat ist nur gültig für Erzeugnisse, die mit dem Prüfgegenstand übereinstimmen. Ausgestellt von der durch die DAkkS nach DIN EN ISO/IEC 17065 akkreditierte Zertifizierungsstelle. Die Akkreditierung gilt nur für den in der Urkundenanlage D-ZE-11052-02-01 aufgeführten Akkreditierungsumfang.  
The issue of this certificate is based upon an evaluation in accordance with the Certification Program CERT FSP1 V1.0:2017 in its actual version, whose results are documented in Report No. 968/FSP 1358.02/23 dated 2023-05-08. This certificate is valid only for products, which are identical with the product tested. Issued by the certification body accredited by DAkkS according to DIN EN ISO/IEC 17065. The accreditation is only valid for the scope listed in the annex to the accreditation certificate D-ZE-11052-02-01.

**TÜV Rheinland Industrie Service GmbH**  
Bereich Automation  
Funktionale Sicherheit  
Am Grauen Stein, 51105 Köln

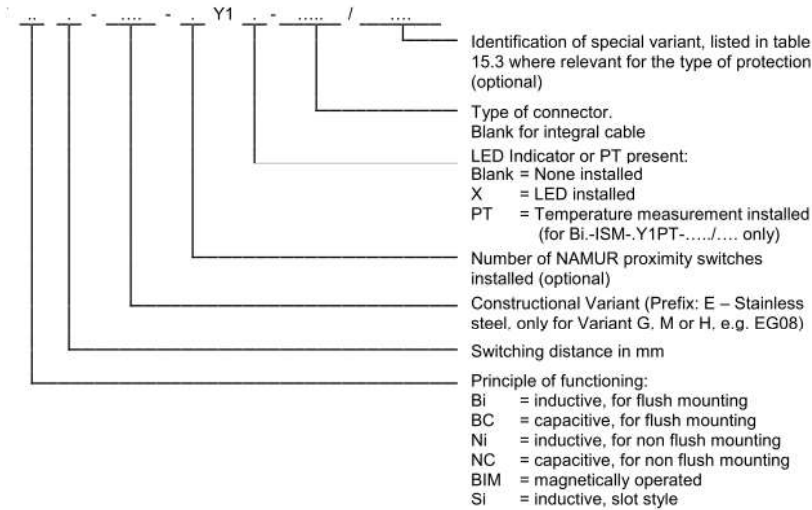
Köln, 2023-05-12

Certification Body Safety & Security for Automation & Grid

  
Dipl.-Ing. Gebhard Bouwer



**Type designation key:**



The range of two-wire proximity switches type ... -....Y1. -.... /.... consists of different designs divided into ten groups. The identification of the appropriate type group is related to the designs and can be determined from the following table:

Constructional Variant	Type Group	Constructional Variant	Type Group	Constructional Variant	Type Group	Constructional Variant	Type Group
AKT	A	.G182	A	K12	A	PST	M
BKT	S	.G19...Y1...	A	K20...Y1...	A	Q05	M
BRY	GD	.G19...Y1X...	AX	K20...Y1X...	AX	Q08	M
CA25	G	.G20...Y1...	A	K30	A	Q10	A
CA40	G	.G20...Y1X...	AX	K33	G	Q10S	A
CK40	G	.G28	A	K34	G	Q11	M
CP40	G	.G30...Y1...	A	K40	G	Q11S	A
CP80	G	.G30...Y1X...	AX	K90...Y1...	G	Q12	A
DS20	AD	.G47	G	K90...Y1X...	GX	Q14	A
DSC26	MD	.GS880	M	M12...Y1...	A	Q20	A
DSU26	AD	.H04	K	M12...Y1X...	AX	Q25	G
DSU35	AD	.H06	M	M18...Y1...	A	Q30	G
FST	M	.H12	A	M18...Y1X...	AX	Q5.5	K
.G05	K	.H6.5	K	M30...Y1...	A	Q8.5	K
.G08	M	.HS540	K	M30...Y1X...	AX	Q80	G
.G10	M	.HS865	M	MP...Y1...	G	QF5.5	K
.G12...Y1...	A	.IKE	A	MP...Y1X...	GX	QST	M
.G12...Y1X...	AX	.IKT	A	NST	M	S12...Y1...	A
.G13	A	.INT	K	P12...Y1...	A	S12...Y1X...	AX
.G14...Y1...	A	.ISM	A	P12...Y1X...	AX	S18...Y1...	A
.G14...Y1X...	AX	.K08...Y1...	S	P18...Y1...	A	S18...Y1X...	AX
.G18...Y1...	A	.K09	S	P18...Y1X...	AX	S30...Y1...	A
.G18...Y1X...	AX	.K10	S	P30...Y1...	A	S30...Y1X...	AX
.G180	A	.K11...Y1...	A	P30...Y1X...	AX	T12	A
.G181	A	.K11...Y1X...	AX	PSM	M		

**Safety-related parameters:**

Parameter	Value
Device Type	A (acc. to IEC 61508-2)
Total Failure Rate $\lambda_S + \lambda_D$	28.5 FIT
Lambda dangerous = Lambda dangerous undetected $\lambda_{DU}$	3.1 FIT
Lambda safe $\lambda_S$	25.2 FIT
Safe Failure Fraction (SFF)	88.4%
MTTF <sub>d</sub>	36 471 a
PFH (1001)	3.1 E-09 1/h
PFD <sub>av</sub> (T = 20a) (1001)	2.7 E-04
Safety Capability (the requested HFT of the relevant application standard has to be considered)	SIL 3, PL e

Remark: 1 FIT = 1 E-09 1/h, Failure rates of the electronic components as per Siemens SN 29500

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